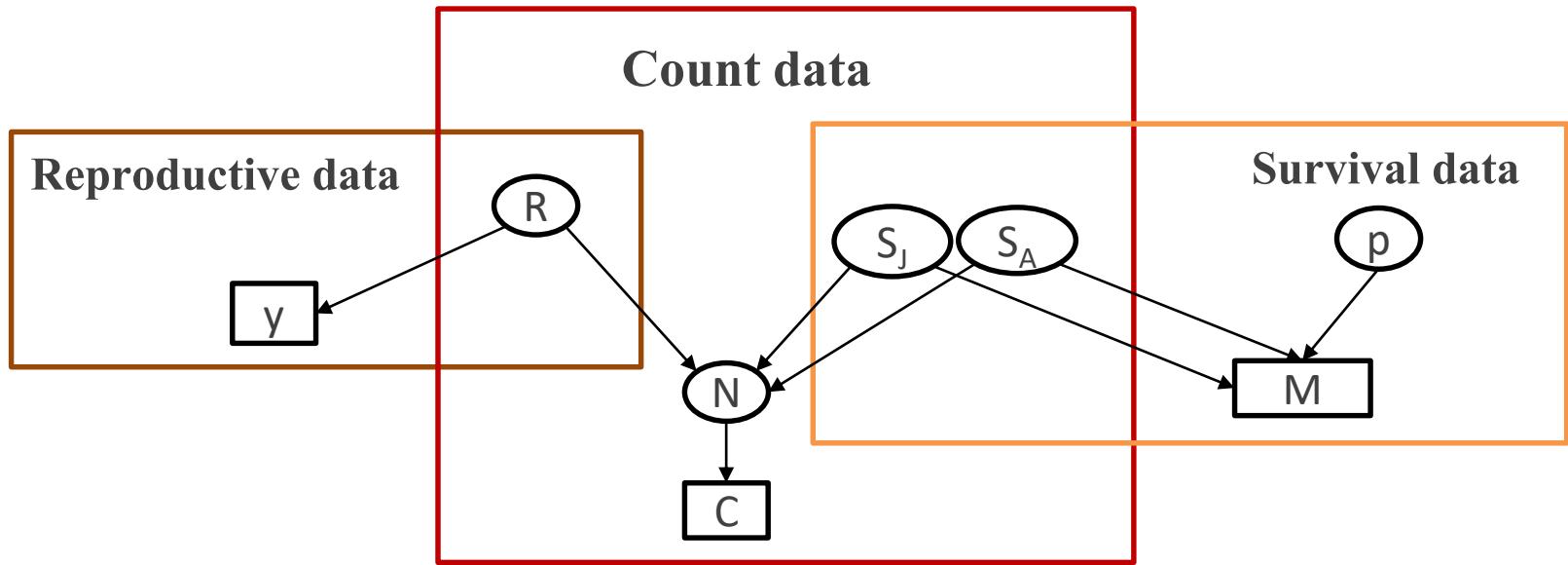
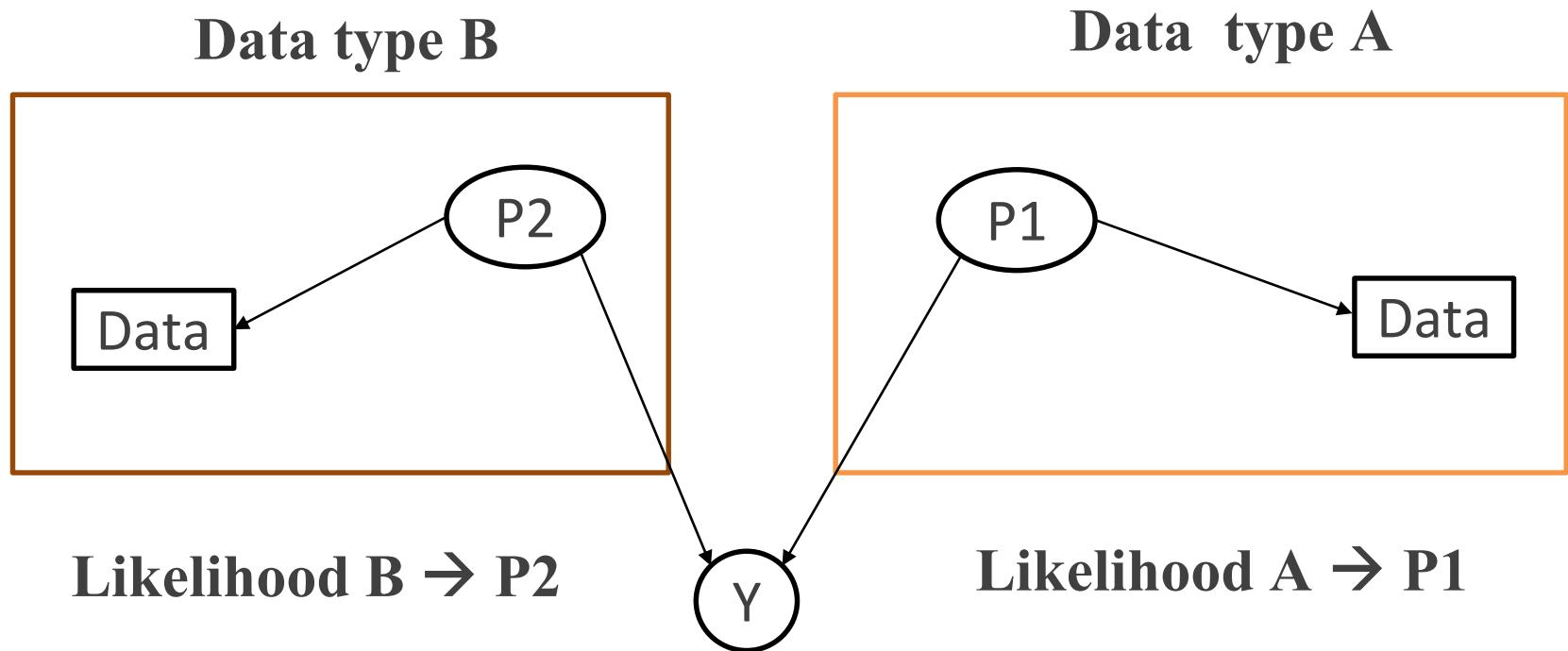


Violations of assumptions in INTEGRATED POPULATION MODELS: Consequences and Diagnostics

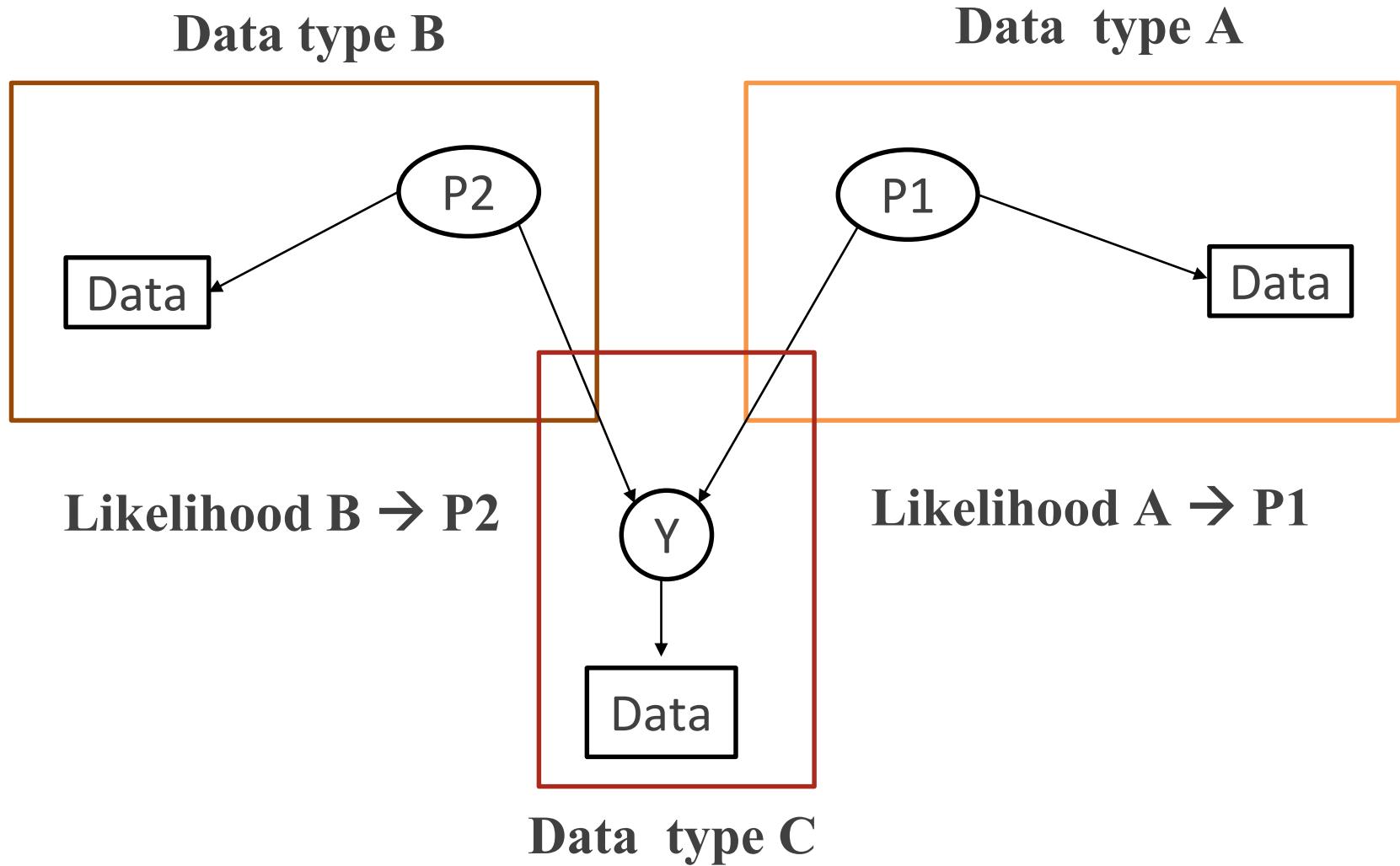


INTEGRATED MODELS



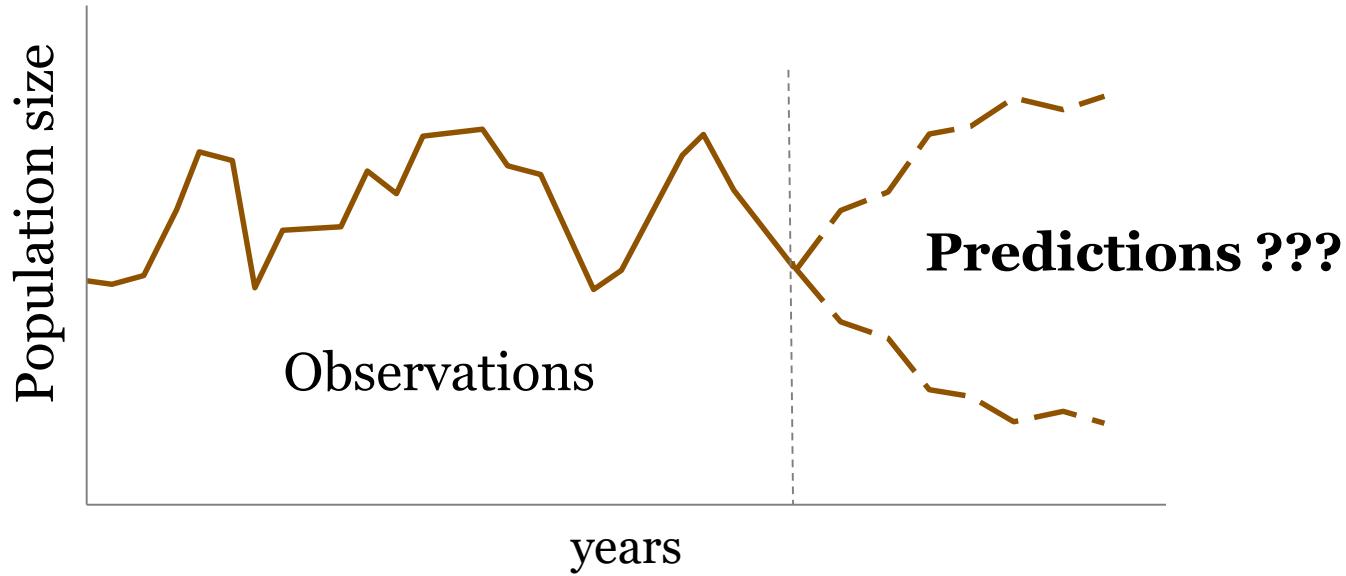
Likelihood Model = Likelihood B x Likelihood A

INTEGRATED MODELS



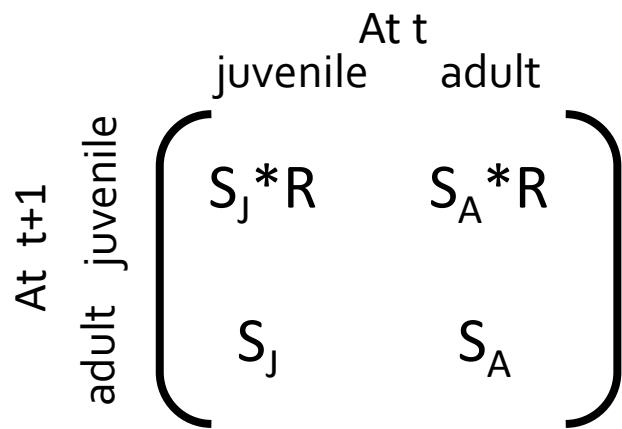
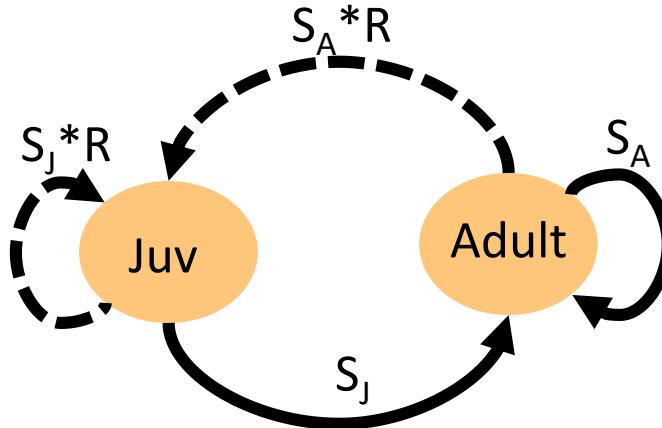
Likelihood Model = Likelihood B x Likelihood A x Likelihood C

THE NEED TO PREDICT POPULATION DYNAMICS



**Conservation
Management
Fundamental research**

POPULATION MODELS



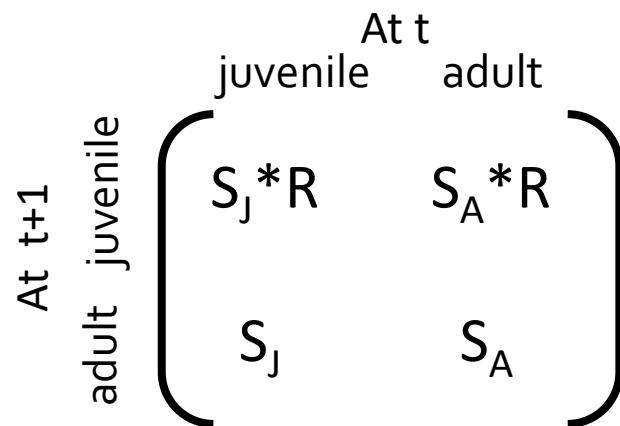
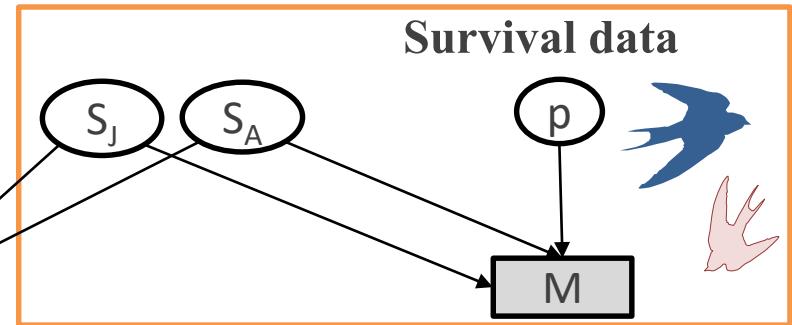
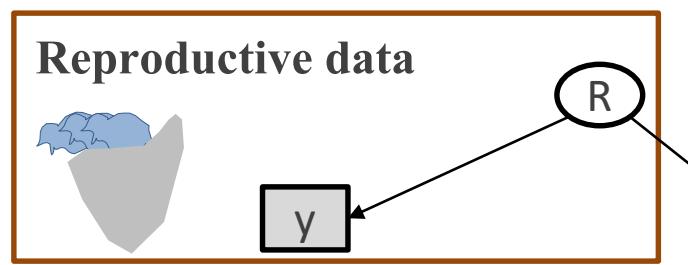
$$N_{Juv}[t-1] \sim dpois(R * N[t-1])$$

$$N_{adj}[t] \sim dbin(S_J, N_{Juv}[t-1])$$

$$N_{ad}[t] \sim dbin(S_A, N[t-1])$$

$$N[t] = N_{adj}[t] + N_{ad}[t]$$

POPULATION MODELS



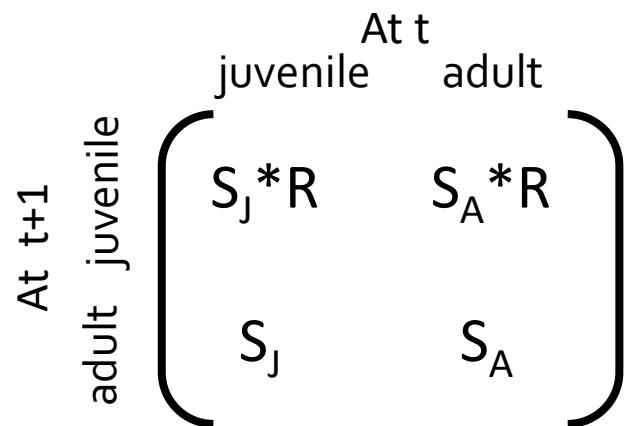
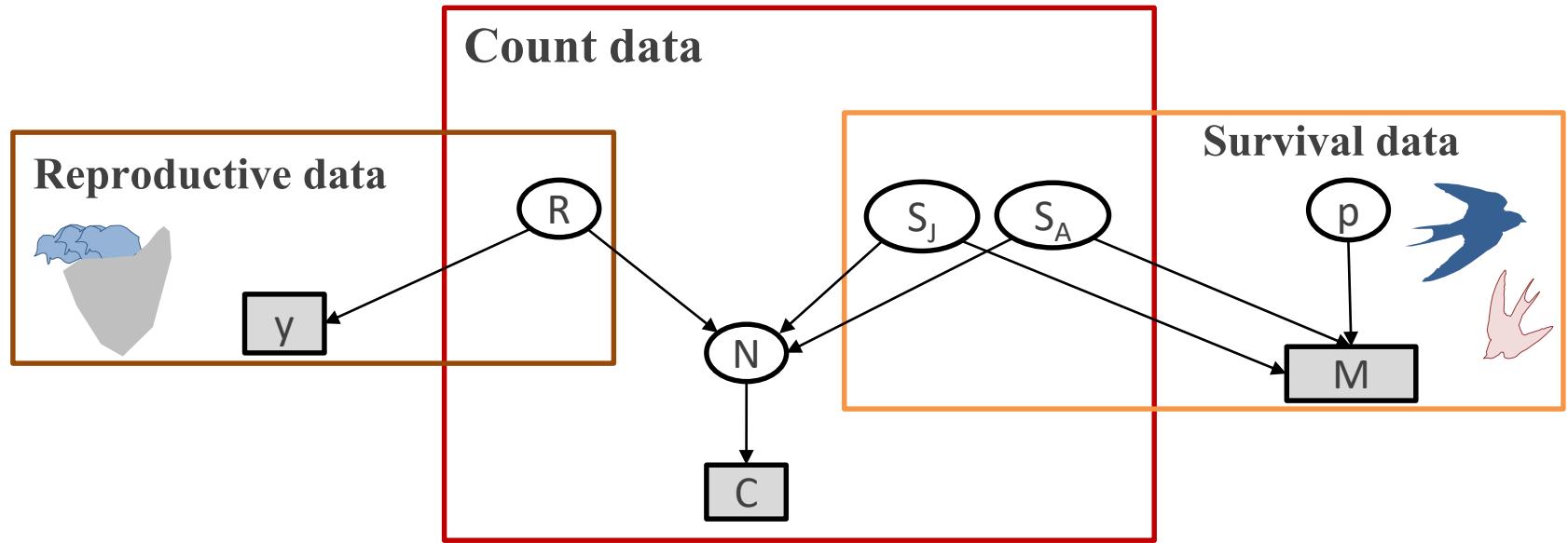
$$NJuv[t-1] \sim dpois(R * N[t-1])$$

$$Nadj[t] \sim dbin(S_J, NJuv[t-1])$$

$$Nad[t] \sim dbin(S_A, N[t-1])$$

$$N[t] = Nadj[t] + Nad[t]$$

INTEGRATED POPULATION MODELS



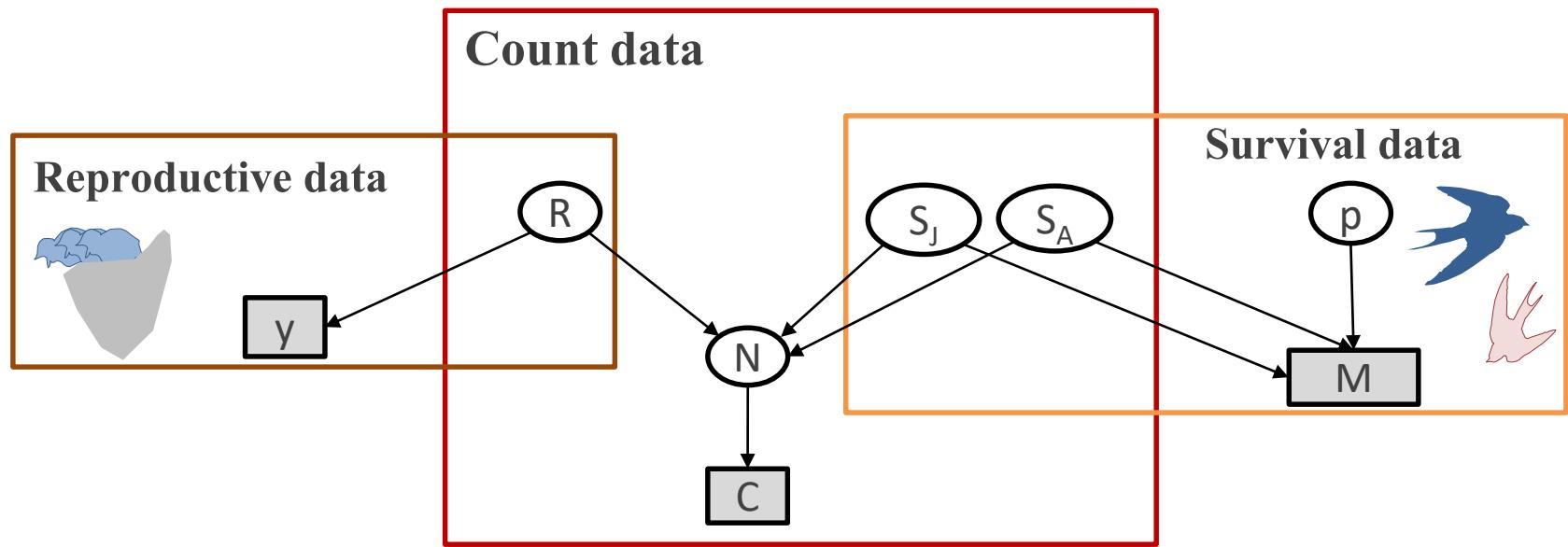
$$N_{\text{Juv}}[t-1] \sim \text{dpois}(R * N[t-1])$$

$$N_{\text{adj}}[t] \sim \text{dbin}(S_J, N_{\text{Juv}}[t-1])$$

$$N_{\text{ad}}[t] \sim \text{dbin}(S_A, N[t-1])$$

$$N[t] = N_{\text{adj}}[t] + N_{\text{ad}}[t]$$

INTEGRATED POPULATION MODELS

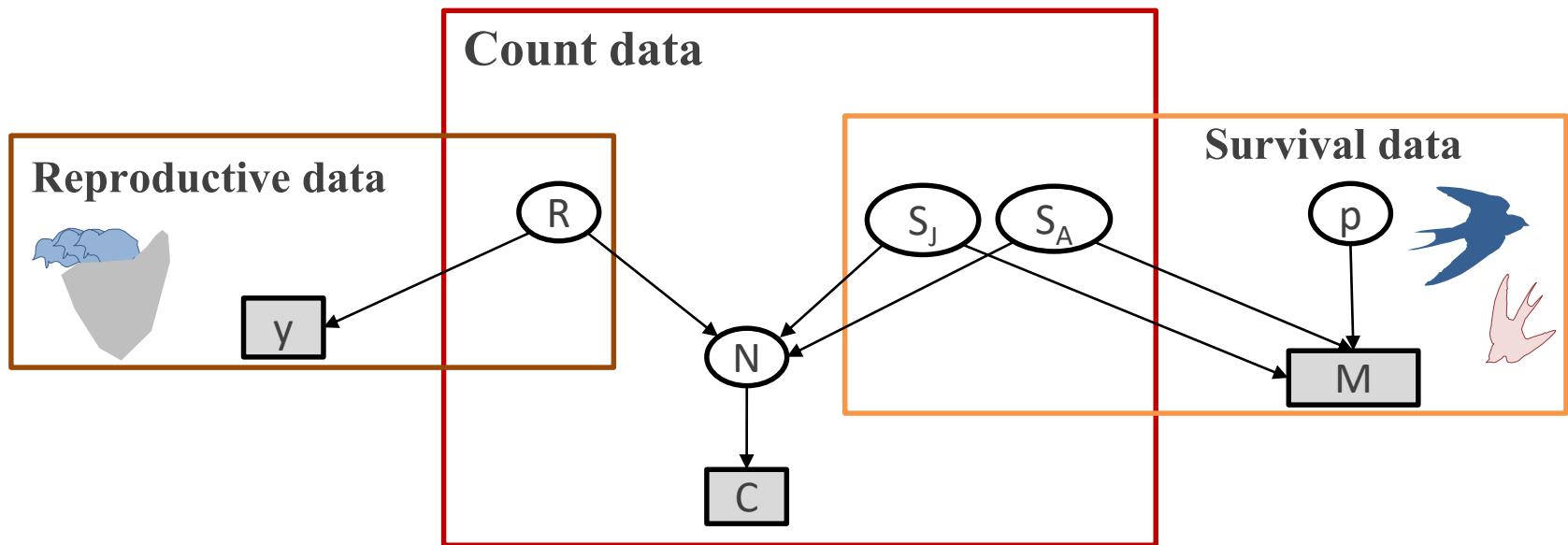


Integrated models = combine data

Joint Likelihood = \prod likelihood of different datasets

If datasets are independent!

INTEGRATED POPULATION MODELS

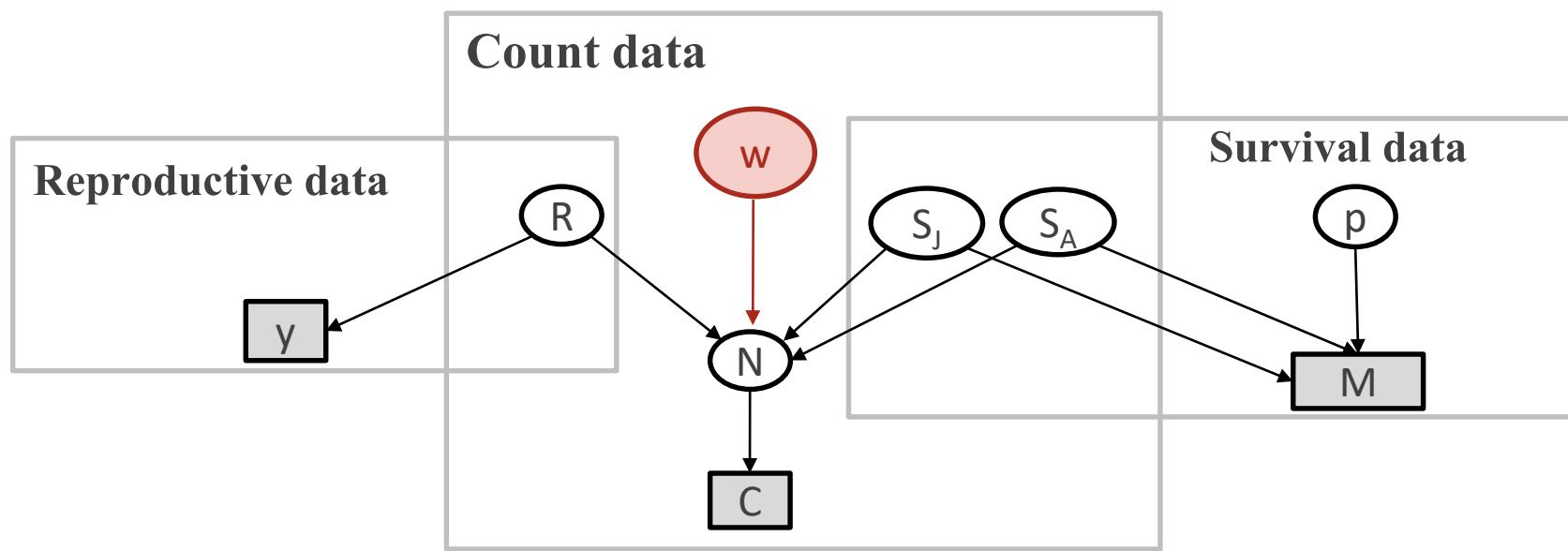


Advantages:

- lower uncertainty
- estimate supplemental parameter

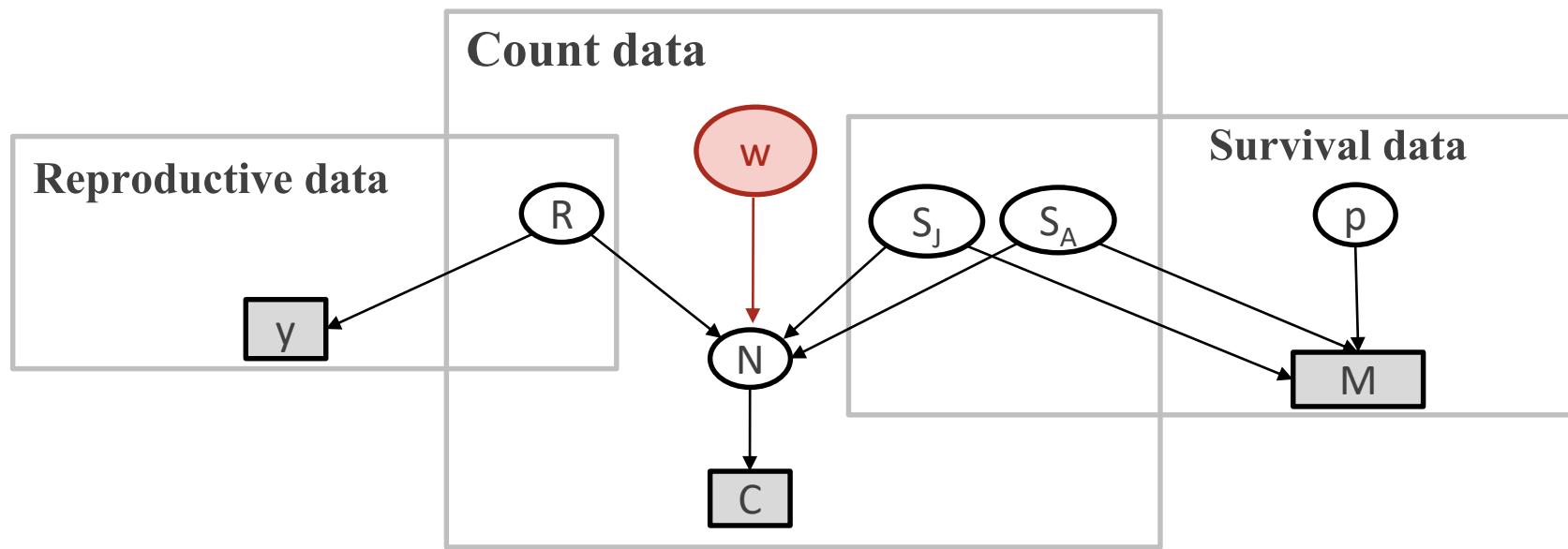
RIECKE ET AL 2019: THE PROBLEM OF THE SUPPLEMENTAL PARAMETER

Immigration (for instance)



RIECKE ET AL 2019: THE PROBLEM OF THE SUPPLEMENTAL PARAMETER

Immigration (for instance)

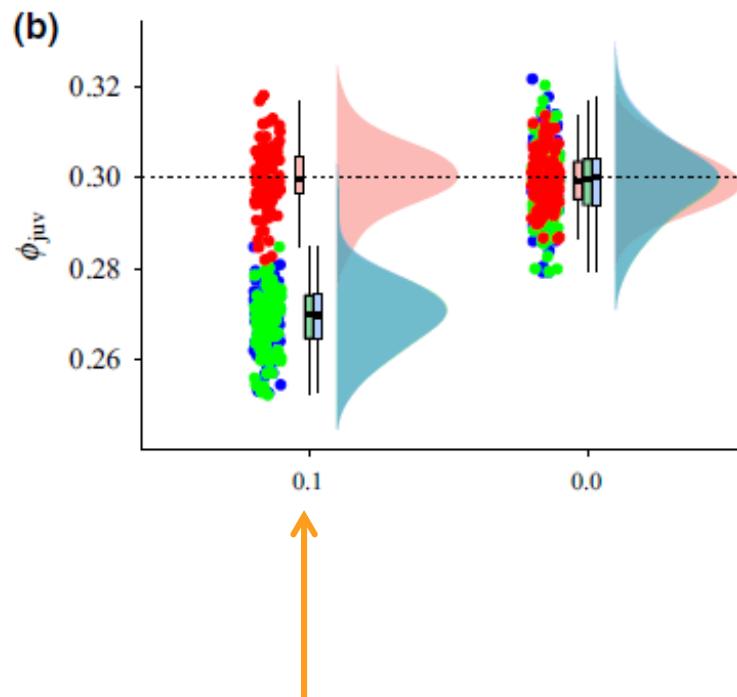
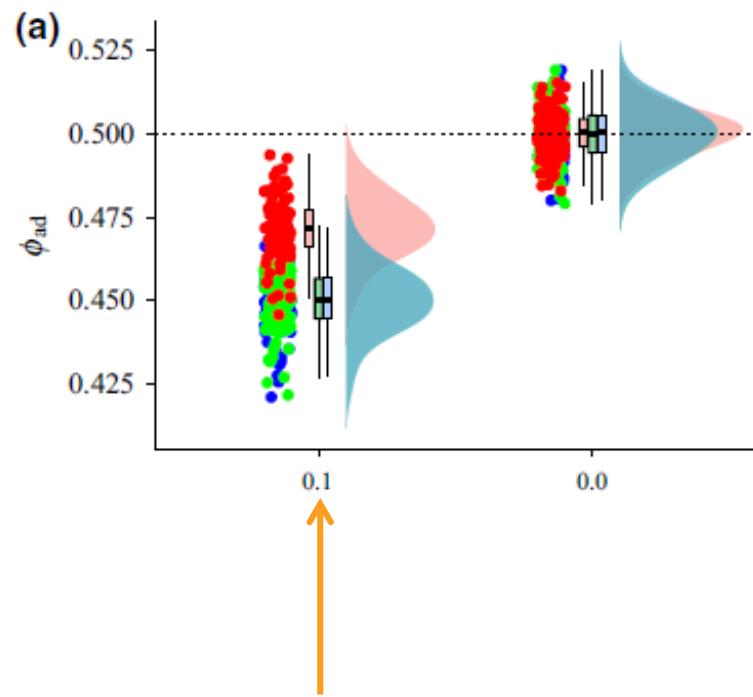


**BUT: What if there is another mechanism
that we do not know about?**

RIECKE ET AL 2019: THE PROBLEM OF THE SUPPLEMENTAL PARAMETER

Immigration (for instance)

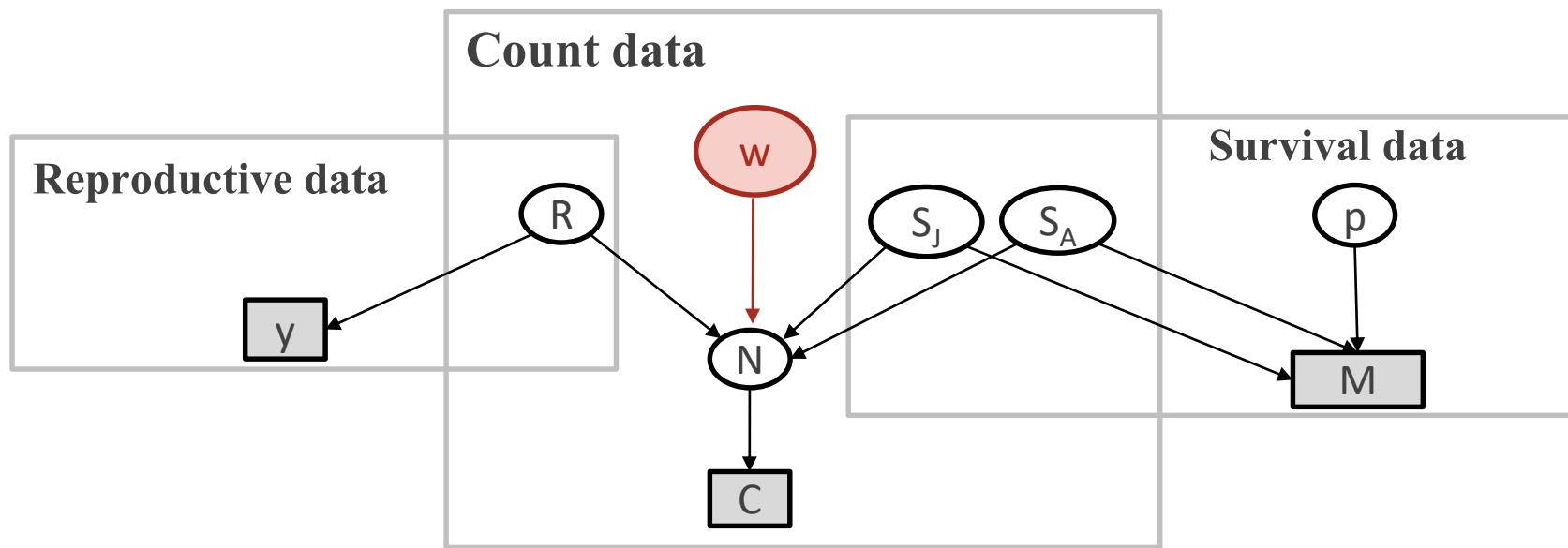
- Simple Survival model
- IPM simple (no immigration)
- IPM immigration



BUT: What if there is also mark loss?

THE PROBLEM OF THE SUPPLEMENTAL PARAMETER

If some assumptions are violated, some parameters are going to be biased



THE PROBLEM OF THE SUPPLEMENTAL PARAMETER

If some assumptions are violated, some parameters
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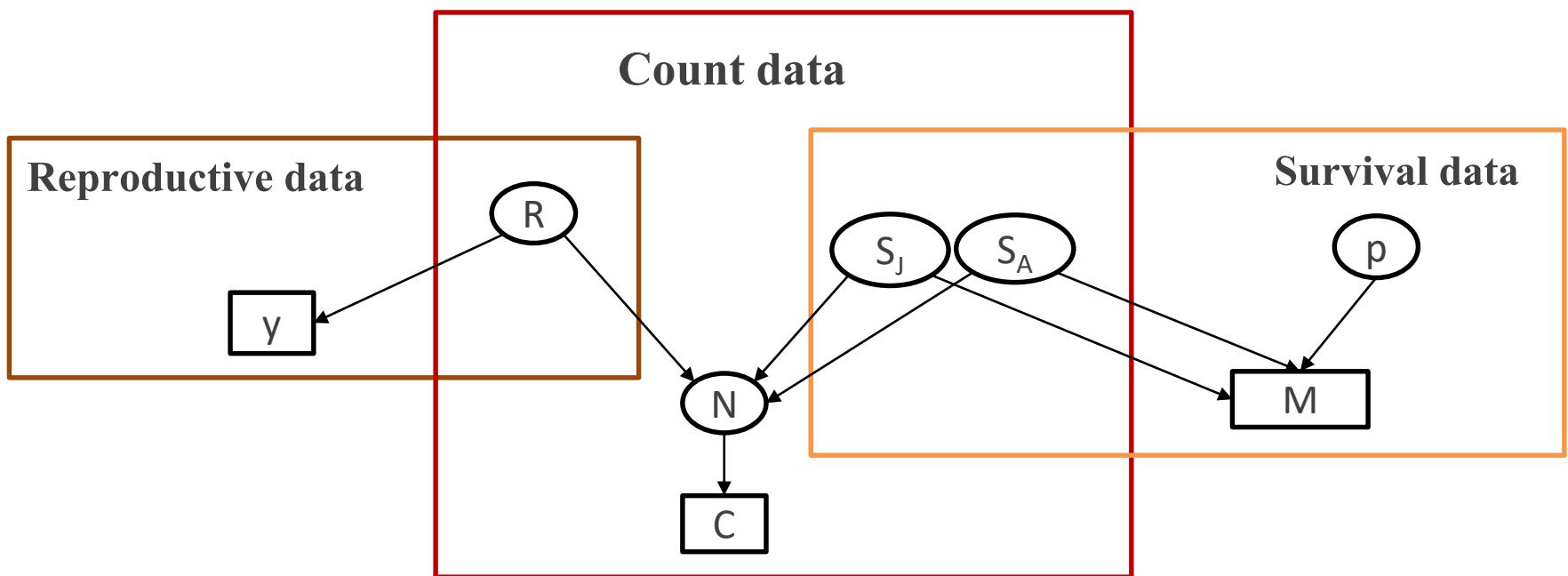
Assumptions:

- Independance of datasets
- Distributions of parameters
- Heterogeneity in parameters

We also make many assumptions about the chosen
demographic model

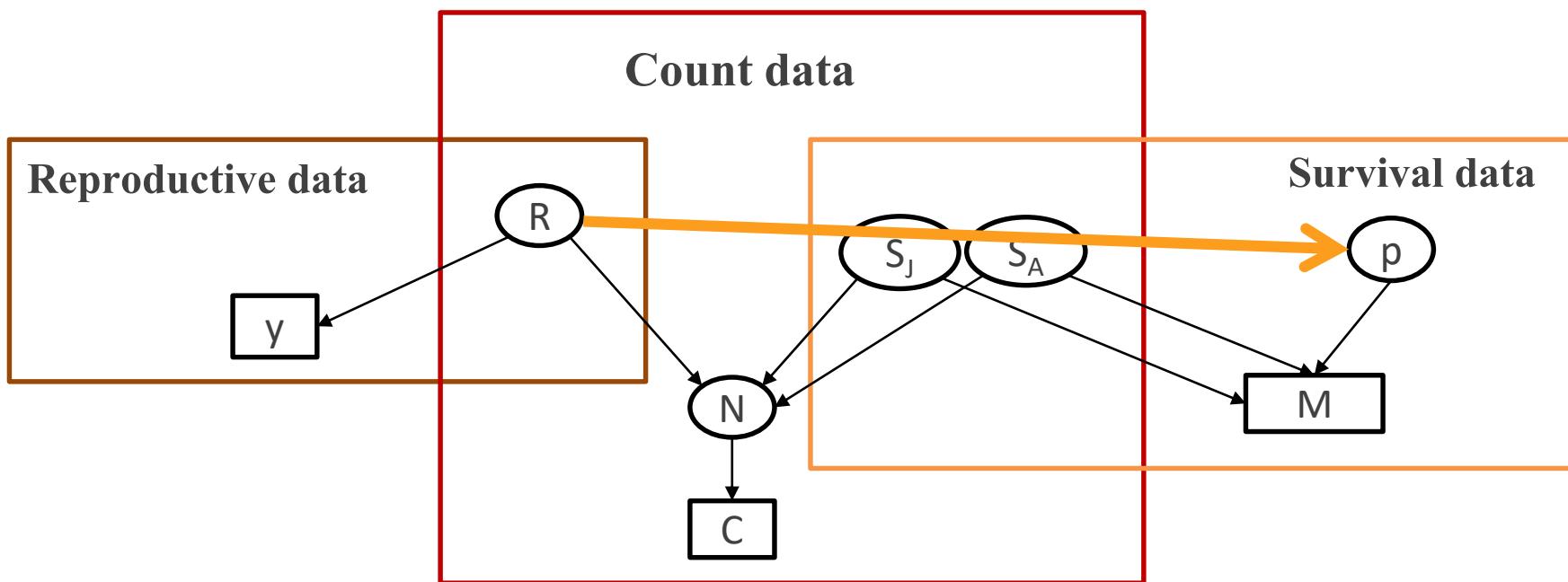
CLASSICAL IPMPOP

BUT: What are the consequences if???



CLASSICAL IPMPOP

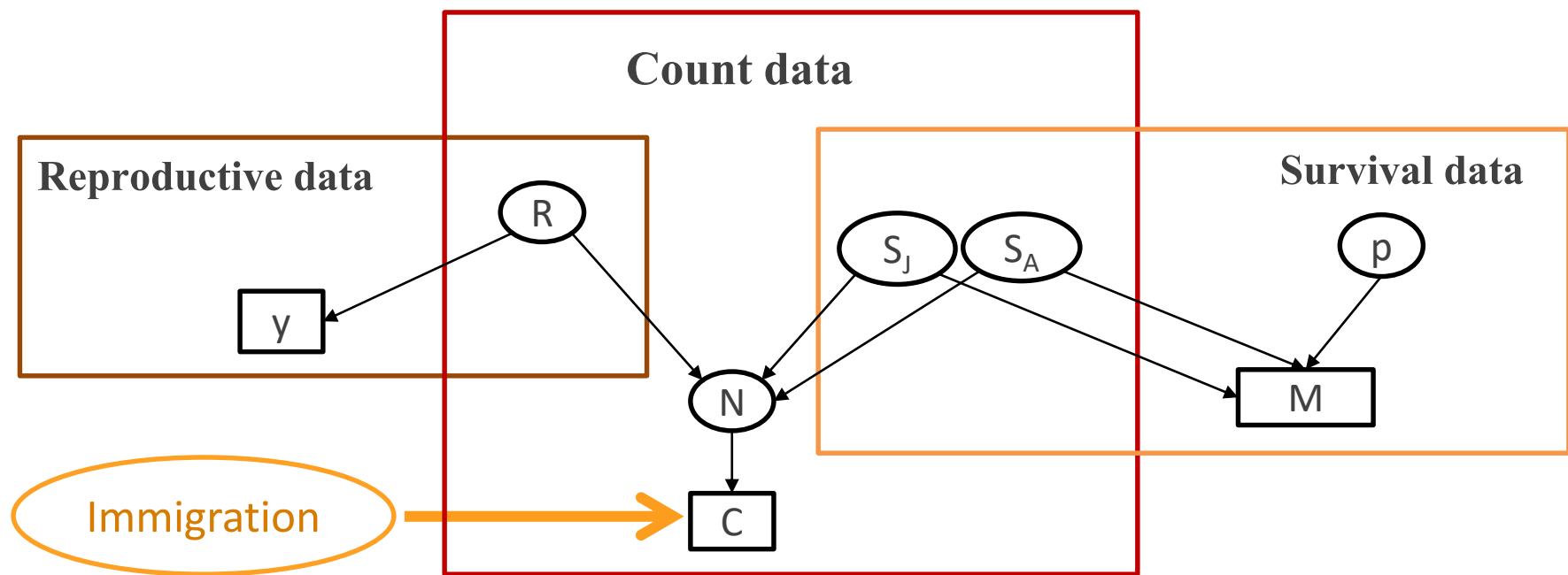
BUT: What are the consequences if???



- Recapture depends on reproduction?

CLASSICAL DEMOGRAPHIC MODELS

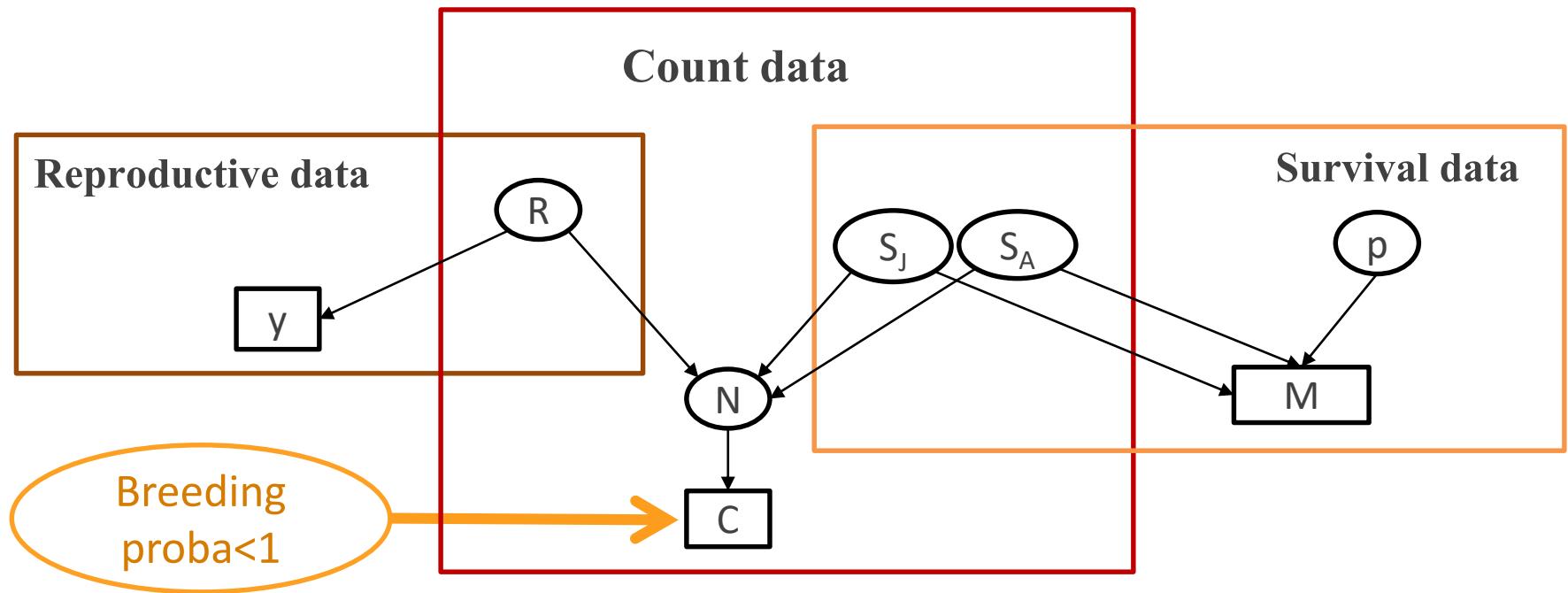
BUT: What are the consequences if???



- Recapture depends on reproduction?
- Immigration?

CLASSICAL IPMPOP

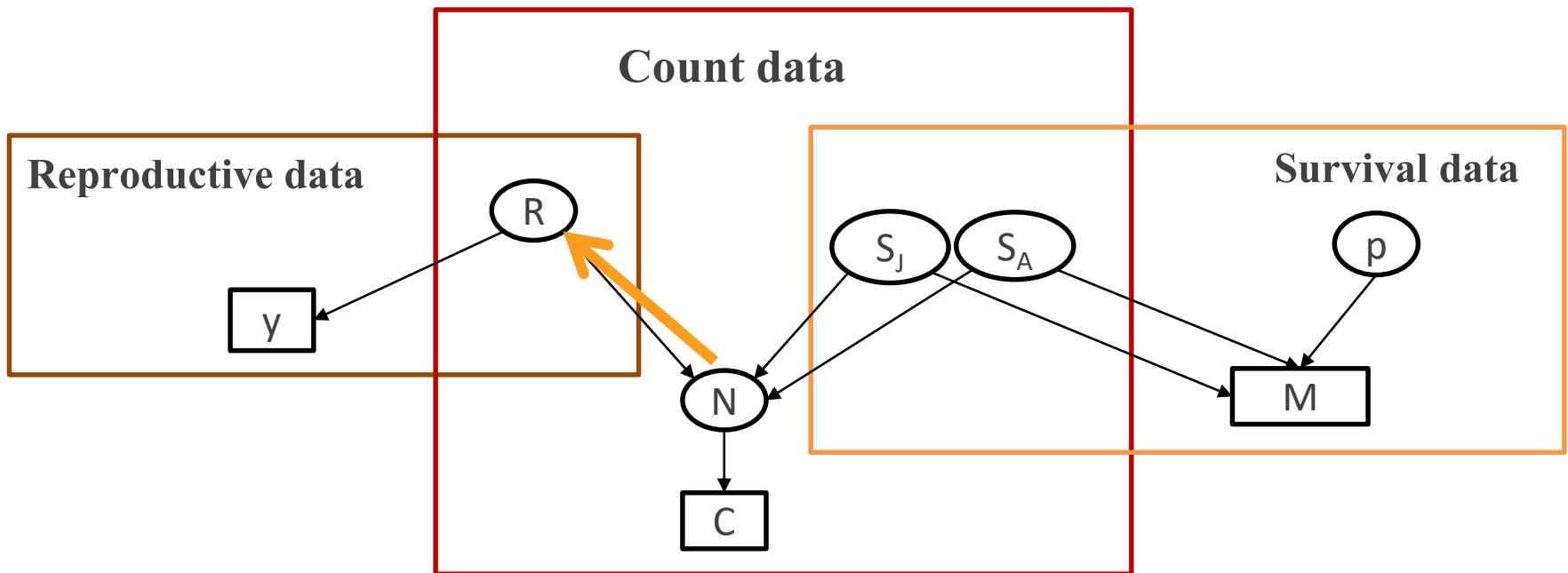
BUT: What are the consequences if???



- Recapture depends on reproduction?
- Immigration?
- Presence of non-breeders

CLASSICAL IPMPOP

BUT: What are the consequences if???



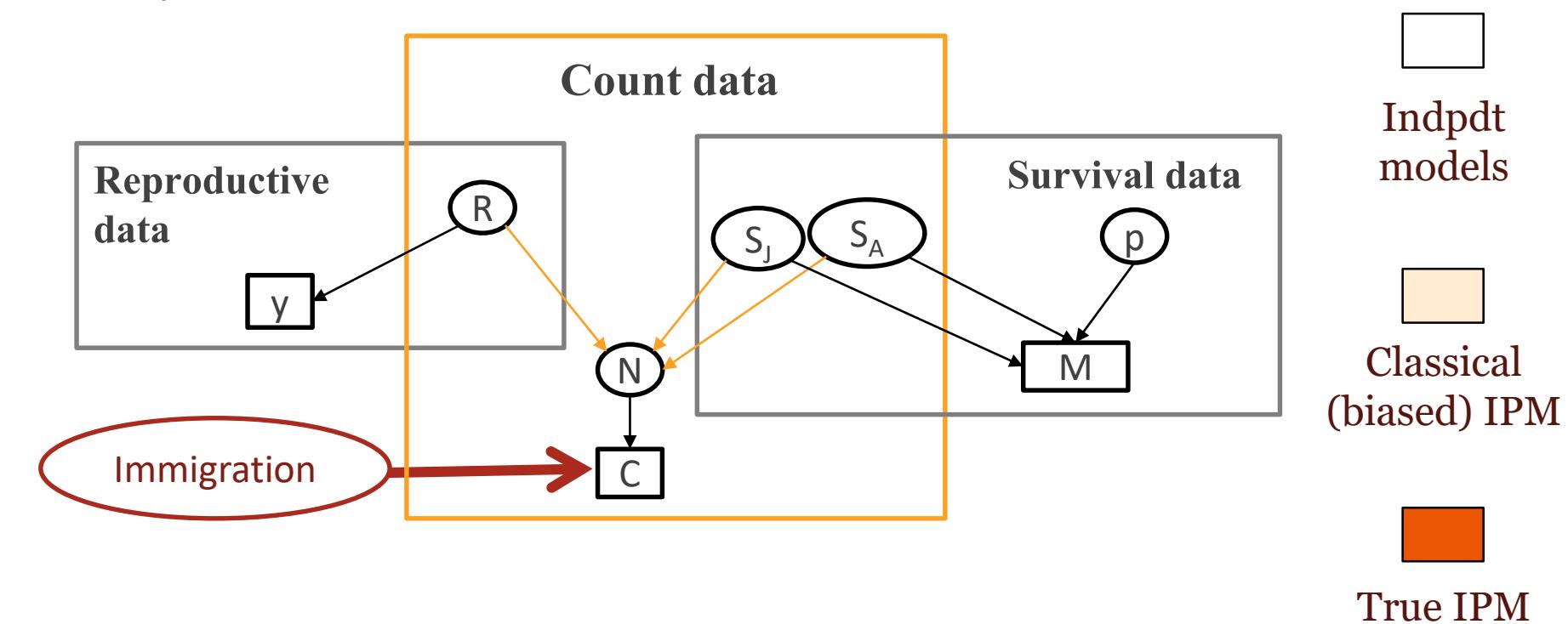
- Recapture depends on reproduction?
- Immigration?
- Presence of non-breeders
- Density-dependent effect

5 DATASETS ANALYZED WITH 3 TYPES OF MODELS

Simulation of data:

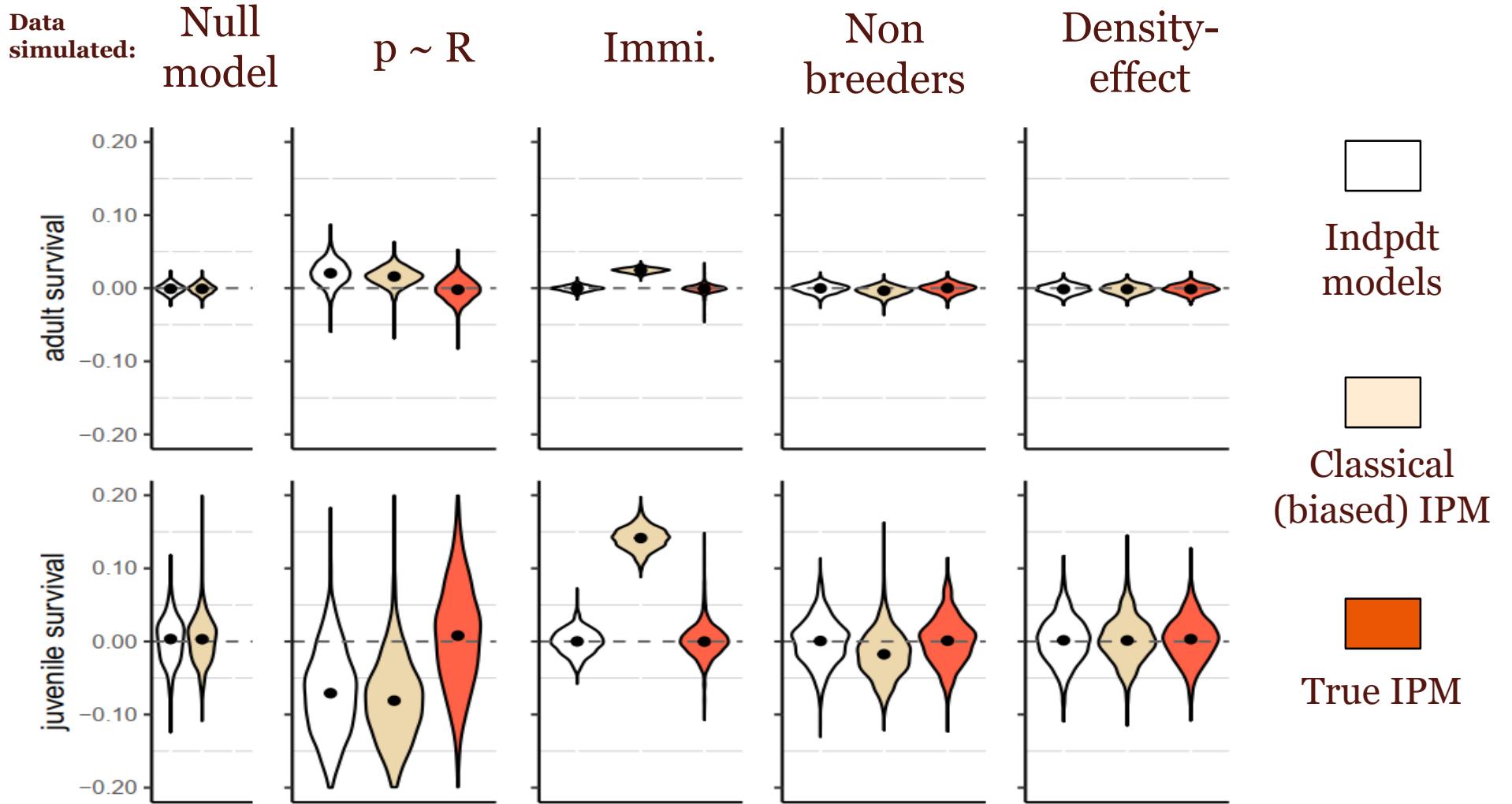
1. Null Model
2. Recapture depends on reproduction
3. Immigration
4. Probability of reproduction < 1
5. Density effect

Analysis of data:



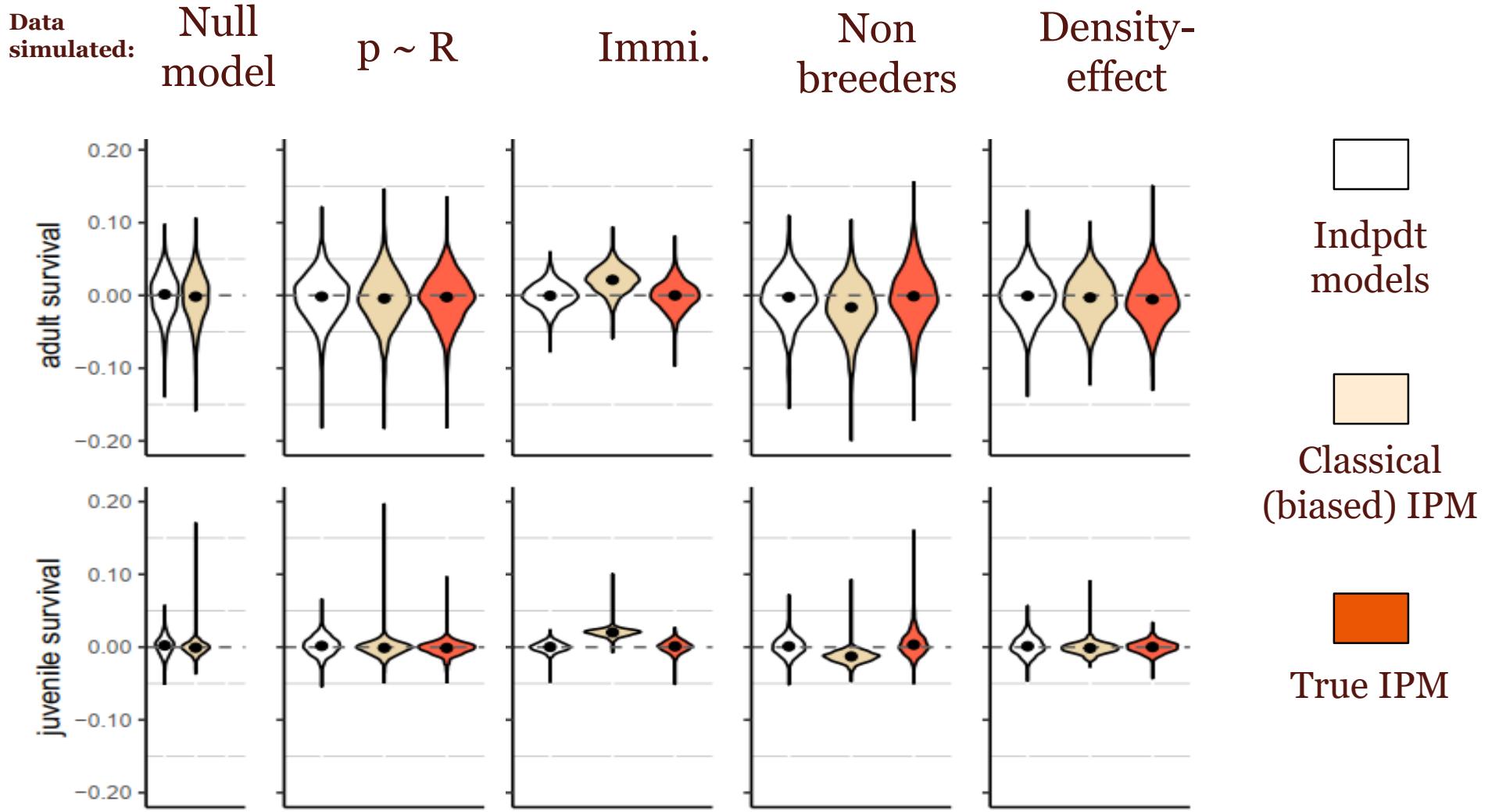
5 DATASETS ANALYZED WITH 3 TYPES OF MODELS

Long-lived species:



5 DATASETS ANALYZED WITH 3 TYPES OF MODELS

Short-lived species:



DIAGNOSTIC TOOLS

How do I know when my model is wrong?

		GOF: survival	GOF: Reproduction	GOF: count	Comparison: CMR model	Residuals	LL Profile
simple IPM	Null	4	3	4	2	73	29
	1. Recapture breeders	20	3	4	2	78	25
	2. Immigration	100	100	100	100	100	88
	3. Non-breeders	5	3	5	5	67	29
	4. Density effect	4	5	6	2	69	24

CONCLUSION

1. For most assumptions, the bias is relatively small. Do simple models whenever possible
2. Parameter with the highest uncertainty will be the one that will be biased → You cannot not know which assumption is violated
3. Diagnostic tests are not sensitive to small bias

Solutions:

1. Compare the results to independent models
2. Do again your model with fewer data! If your model is correct, mean parameters should be similar...

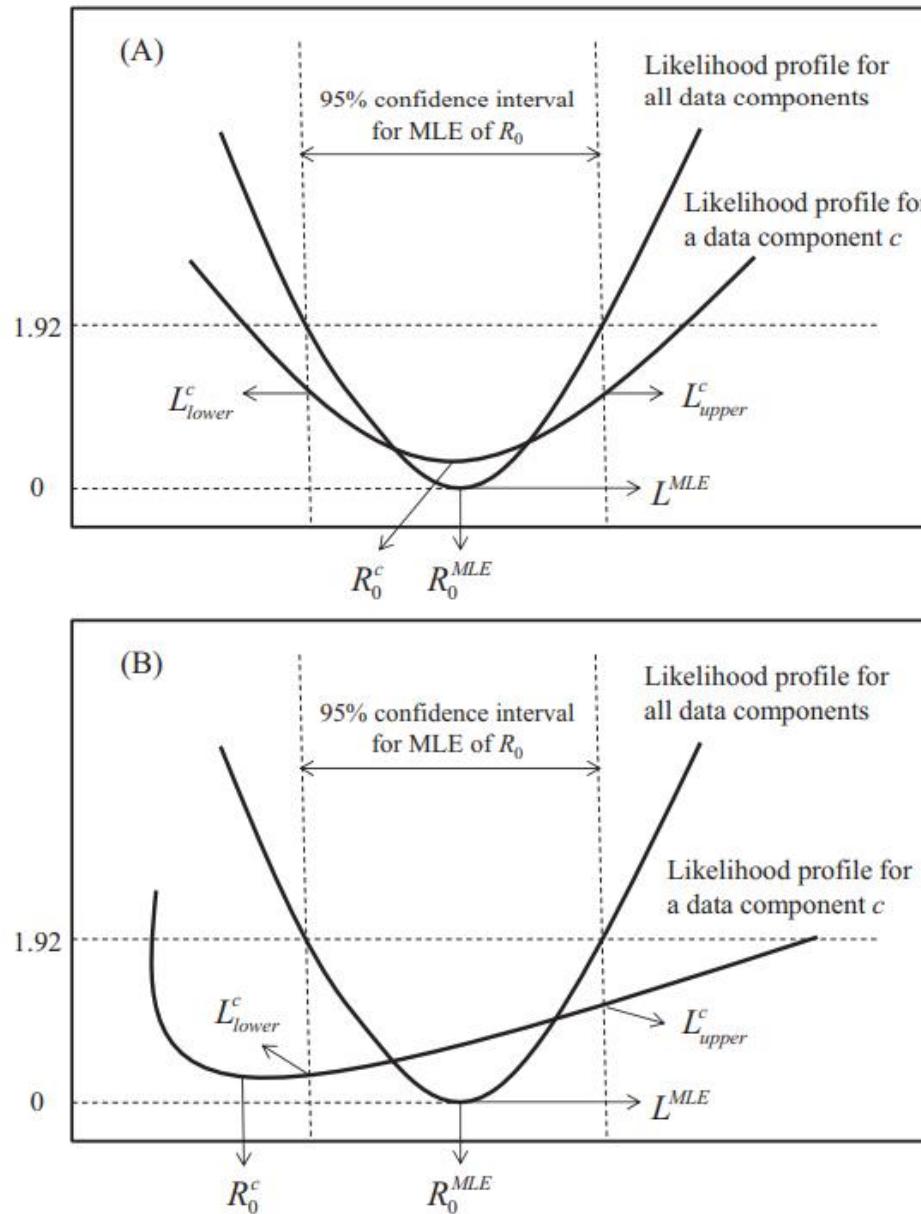
AKNOWLEDGMENTS



vogelwarte.ch

Michael SCHAUB
Daniel Turek

Thank you for your attention



$$\varphi = \begin{cases} \max[(L_c^{\text{lower}} - L^{\text{MLE}}), (L_c^{\text{upper}} - L^{\text{MLE}})], & \text{if } R_0^c \text{ is located within the 95\% confidence interval for } R_0^{\text{MLE}} \\ |L_c^{\text{lower}} - L_c^{\text{upper}}|, & \text{otherwise} \end{cases}$$