

# Algorithmes MCEM VEM et VBEM pour l'estimation d'un processus de Cox log-Gaussien

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# Motivation

Modeling of a spatial phenomenon when data are sampled counts

- A regular grid of quadrats  $A_1, \dots, A_N$  on a  $\mathcal{D} \subset \mathbb{R}^2$
- We observe  $Y_i$  the count in quadrat  
 $i \in \mathcal{O} \subset \mathcal{V} = \{1, \dots, N\}$

3					11	
10	20		5	15		
		1	12		9	
		50				30

# Motivation

Such type of data (counts associated with spatial point processes) are encountered in various fields of applications :

- forestry (counts of trees of a given species)
- ecology (sightings of wild animals)
- epidemiology (disease mapping based on reported infection cases)
- environmental sciences (radioactivity counts)
- agronomy (counts of weeds)
- etc ...

# Objectives

The log-Gaussian Cox process is often used for modeling this type of data.

1. We derive the parameters estimations by a moments method
2. We propose a MCEM algorithm
3. We present a preliminary comparison
4. We propose a VEM and a VBEM algorithm
5. We present some simulation results

# Poisson process

We consider a spatial Poisson process in  $\mathbb{R}^2$  with intensity  $\lambda = \{\lambda(x), x \in \mathcal{D}\}$ .

- $Y_i \sim \mathcal{P}(\Lambda_i)$  with  $\Lambda_i = \int_{A_i} \lambda(x) dx$
- Non stochastic  $\Lambda_i \Rightarrow Y_i \perp Y_j$  for  $i \neq j \Rightarrow$  No statistical correlation between  $Y_i$  and  $Y_j$  for  $i \neq j$
- In practice
  - there may exist a stochastic dependence between the numbers of points observed in non-overlapping domains
  - the intensity of the point process is often uncertain in areas without data

⇒ More convenient and more parsimonious to use a stochastic modeling of this intensity

# Cox process

We consider a spatial Poisson process in  $\mathbb{R}^2$  with stochastic intensity  $\lambda = \{\lambda(x), x \in \mathcal{D}\}$ .

- $\lambda(x) = \exp(\beta) \exp(S(x))$
- $S(\cdot)$  is a Gaussian random field centered with variance  $\sigma^2$  and exponential covariance function

$$\text{Cov}(S(x_1), S(x_2)) = \sigma^2 \exp(-\alpha||x_1 - x_2||)$$

- $Y_i | \Lambda_i \sim \mathcal{P}(\Lambda_i)$  with  $\Lambda_i = \int_{A_i} \lambda(x) dx$  approximated by  $\Lambda_i = |A_i| \exp(\beta) \exp(S_i)$  where  $S_i$  is the value of  $S$  at the center of  $A_i$ .
- $Y_i | \Lambda_i \perp Y_j | \Lambda_j$  for  $i \neq j$ .
- 3 parameters in the model  $\theta = (\beta, \sigma, \alpha)$ ,  $\beta \in \mathbb{R}$ ,  $\alpha, \sigma \in \mathbb{R}_+^*$ .

# Moments method

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By straightforward calculations we obtain :

$$E(Y_i) = |A_i| \exp(\sigma^2/2) \exp(\beta) \quad (1)$$

$$\begin{aligned} \text{Var}(Y_i) &= |A_i| \exp(\sigma^2/2) \exp(\beta) \\ &\quad + |A_i|^2 \exp(\sigma^2) \exp(2\beta)(\exp(\sigma^2) - 1) \end{aligned} \quad (2)$$

$$E(Y_i Y_j) = |A|^2 \exp(2\beta) \exp(\sigma^2(1 + e^{-\alpha r})) \quad (3)$$

where  $r = |i - j|$

# $\beta$ and $\sigma^2$ estimations

By equations (1) and (2) :

$$\sigma^2 = \ln \left[ \frac{\text{Var}(Y) - E(Y) + E(Y)^2}{E(Y)^2} \right] \quad (4)$$

$$\beta = \ln \left[ \frac{E(Y)}{|A| \sqrt{\frac{\text{Var}(Y) - E(Y) + E(Y)^2}{E(Y)^2}}} \right] \quad (5)$$

$Y_i, \forall i$ , are identically distributed. By the weak law of large number,  $E(Y_i)$  and  $\text{Var}(Y_i)$  are estimated by  $\bar{Y} = \frac{1}{\#\mathcal{O}} \sum_{i \in \mathcal{O}} Y_i$

and  $\hat{V}(Y) = \frac{1}{\#\mathcal{O}} \sum_{i \in \mathcal{O}} (Y_i - \bar{Y})^2$

$\Rightarrow \hat{\beta}$  and  $\hat{\sigma}^2$  are obtained by replacing  $E(Y_i)$  and  $\text{Var}(Y_i)$  by  $\bar{Y}$  and  $\hat{V}(Y)$  in (4) and (5).

# $\alpha$ estimation

Using equation (3) we obtain :

$$\hat{\alpha} = -\frac{1}{r} \ln \left[ \frac{1}{\hat{\sigma}^2} \ln \left[ \frac{\hat{E}(Y_i Y_j)}{|A_i|^2 \exp(2\hat{\beta})} \right] - 1 \right]$$

$E(Y_i Y_j)$  is estimated by using the variogram estimation.  
Indeed, since :

$$\begin{aligned}\gamma(r) &= \frac{1}{2} \text{Var}(Y(x) - Y(x + r)) \\ &= \text{Var}(Y) - \text{Cov}(Y(x), Y(x + r))\end{aligned}$$

We easily deduce

$$\hat{E}(Y_i Y_j) = \hat{\text{Var}}(Y) - \hat{\gamma}(r) + \bar{Y}^2$$

where :

$$\hat{\gamma}(r) = \frac{1}{2\#\mathcal{O}_r} \sum_{\mathcal{O}_r} (Y_i - Y_j)^2$$

# Remarks about the moments method

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- These estimators are easily calculated
- But these estimators are not optimal

➡ Maximum likelihood estimators

# MCEM algorithm

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- Observations  $Y_i, i \in \mathcal{O} \subset \mathcal{V} = \{1, \dots, N\}$ .
- Hidden variables  $\begin{cases} S_i & i \in \mathcal{V} \\ Y_i & i \in \bar{\mathcal{O}} = \mathcal{V} \setminus \mathcal{O} \end{cases}$
- Parameters  $\theta = (\alpha, \beta, \sigma), \beta \in \mathbb{R}, \alpha, \sigma \in \mathbb{R}_+^\star$ .
- $\text{Var}(S_1, \dots, S_N) = \Sigma = \sigma^2 U$

# EM algorithm

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- E-step : Calculation of  $p(s, y_{\bar{O}}|y_{\mathcal{O}}, \theta^{(t)})$
- M-step :

$$\operatorname{argmax}_{\theta} F(\theta|\theta^{(t)}) = \operatorname{argmax}_{\theta} E \left[ \ln p(S, y_{\mathcal{O}}, Y_{\bar{O}}|\theta) | y_{\mathcal{O}}, \theta^{(t)} \right]$$

# How to simulate from $p(s|y_{\mathcal{O}}; \theta^{(t)})$ ?

How to simulate from  $p(s|y_{\mathcal{O}}; \theta^{(t)})$  ?

We use the algorithm given by Emery and Hernandez  
(Computers & Geosciences , 2010)

1. Simulate from  $p(s_{\mathcal{O}}|y_{\mathcal{O}}; \theta^{(t)})$  (Gibbs sampler)
2. Simulate from  $p(s_{\bar{\mathcal{O}}}|s_{\mathcal{O}})$  (easy using any multivariate Gaussian simulation algorithm)

# The Gibbs sampler

The Gibbs sampler consists in iterating for  $i \in \mathcal{O}$  :

1. Simulate  $S_i|S_{\mathcal{O}_{-i}}$ . Let  $s'_i$  denote the new simulated value of  $S_i$
2. Simulate a uniform random variable  $U$  on  $[0, 1]$ .
3. If  $p_i U < p'_i$  substitute  $s'_i$  for  $s_i$

where :

$$p_i = P[Y_{\mathcal{O}} = y_{\mathcal{O}} | S_i = s_i, S_{\mathcal{O}_{-i}} = s_{\mathcal{O}_{-i}}]$$

$$= \exp(-\Lambda_i) \frac{\Lambda_i^{y_i}}{y_i!} \prod_{j \in \mathcal{O}_{-i}} \exp(-\Lambda_j) \frac{\Lambda_j^{y_j}}{y_j!}$$

$$p'_i = P[Y_{\mathcal{O}} = y_{\mathcal{O}} | S_i = s'_i, S_{\mathcal{O}_{-i}} = s_{\mathcal{O}_{-i}}]$$

$$= \exp(-\Lambda'_i) \frac{\Lambda'_i^{y_i}}{y_i!} \prod_{j \in \mathcal{O}_{-i}} \exp(-\Lambda_j) \frac{\Lambda_j^{y_j}}{y_j!}$$

# M step : $\beta$ and $\sigma^2$ update

Solving  $\frac{\partial F}{\partial \beta} = 0$  and  $\frac{\partial F}{\partial \sigma^2} = 0$  leads to :

$$\beta^{t+1} = \ln \left[ \frac{\sum_{i \in \mathcal{O}} y_i + \sum_{i \in \bar{\mathcal{O}}} \hat{y}_i^{(t+1)}}{\sum_{i=1}^N |A_i| \int \exp(s_i) p(s|y_{\mathcal{O}}, \theta^{(t)}) ds} \right]$$

$$\sigma^{2(t+1)} = \frac{1}{N} \int s U^{-1} s^T p(s|y_{\mathcal{O}}, \theta^{(t)}) ds$$

where :

$$\begin{aligned}\hat{y}_i^{(t+1)} &= \int y_i p(s, y_{\bar{\mathcal{O}}}|y_{\mathcal{O}}, \theta^{(t)}) ds dy_{\bar{\mathcal{O}}} \\ &= \int y_i p(y_{\bar{\mathcal{O}}}|s, y_{\mathcal{O}}, \theta^{(t)}) p(s|y_{\mathcal{O}}, \theta^{(t)}) ds dy_{\bar{\mathcal{O}}} \\ &= \exp(\beta^{(t)}) |A_i| \int \exp(s_i) p(s|y_{\mathcal{O}}, \theta^{(t)}) ds\end{aligned}$$

# M step : $\alpha$ update

$$\frac{\partial F}{\partial \alpha} = \int p(s, y_{\bar{O}} | y_{\mathcal{O}}, \theta^{(t)}) \left[ -\frac{1}{2} \frac{\partial \ln |U|}{\partial \alpha} - \frac{1}{2\sigma^2} s \frac{\partial(U^{-1})}{\partial \alpha} s \right] ds dy_{\bar{O}}$$

Following Searle (1982) :

$$\frac{\partial \ln |U|}{\partial \alpha} = \text{tr}[U^{-1} \frac{\partial U}{\partial \alpha}]$$

$$\frac{\partial U^{-1}}{\partial \alpha} = -U^{-1} \frac{\partial U}{\partial \alpha} U^{-1}$$

So  $\frac{\partial F}{\partial \alpha} = 0 \Leftrightarrow$

$$\text{tr}(U^{-1} \frac{\partial U}{\partial \alpha}) = \frac{1}{\sigma^2} \int s(U^{-1} \frac{\partial U}{\partial \alpha} U^{-1}) s^T p(s | y_{\mathcal{O}}, \theta^{(t)}) ds$$

solved by a Newton-Raphson algorithm

# Some simulations

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1. Grid size :  $10 \times 40$  ( $N = 400$ )
2. Quadrat size : 0.6 ( $|A_i| = 0.36$ )
3. True values of the parameters  $\beta = 0$ ,  $\sigma^2 = 1$ ,  $\alpha = 1$

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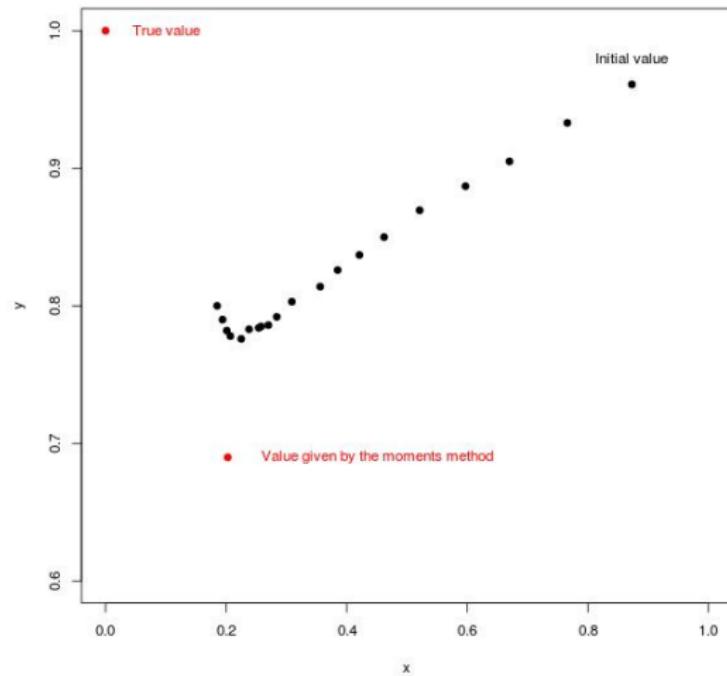
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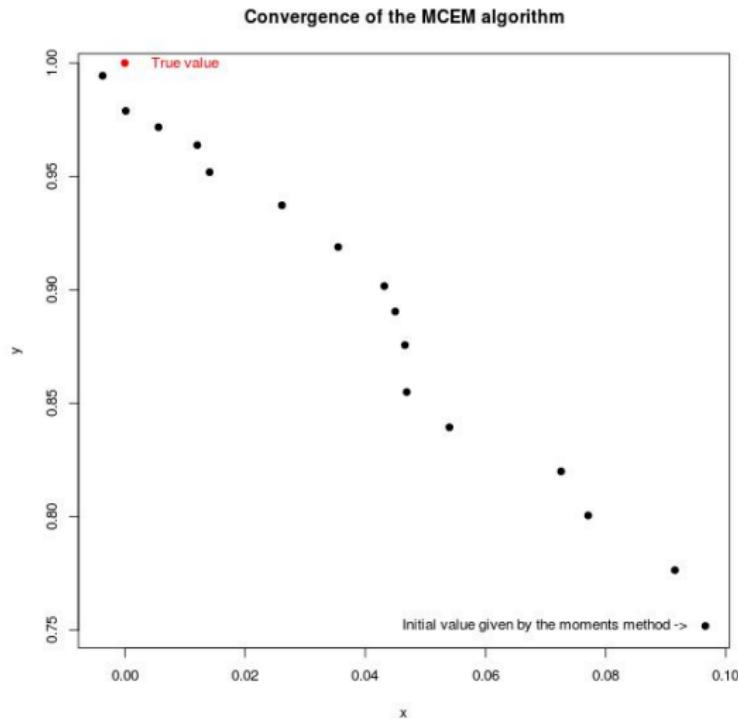
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# Variational methods for estimation

We can prove that for any distribution  $q_s(s)$  on the hidden variables :

$$\begin{aligned}\ln p(y|\theta) &\geq \int q_s(s) \ln p(s, y|\theta) ds - \int q_s(s) \ln q_s(s) ds \\ &\equiv \mathcal{F}(q_s(s), \theta)\end{aligned}$$

The EM algorithm can be written

- E step :  $q_s^{(t+1)} = \operatorname{argmax}_{q_s} \mathcal{F}(q_s(s), \theta^{(t)})$
- M step :  $\theta^{(t+1)} = \operatorname{argmax}_{\theta} \mathcal{F}(q_s^{(t+1)}(s), \theta)$

For the E step the exact solution is  $q_s^{(t+1)} = p(s|y, \theta^{(t)})$ .

For the M step the solution is

$$\theta^{(t+1)} = \operatorname{argmax}_{\theta} E[\ln p(S, y|\theta)|y, \theta^{(t)}]$$

# VEM algorithm

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- Too difficult to evaluate the distribution  $p(s|y, \theta)$

➡ choose a family  $\mathcal{Q}$  of (tractable) distributions

- E step :  $q_s^{(t+1)} = \operatorname{argmax}_{q_s \in \mathcal{Q}} \mathcal{F}(q_s(s), \theta^{(t)})$
- M step :  $\theta^{(t+1)} = \operatorname{argmax}_{\theta} \mathcal{F}(q_s^{(t+1)}(s), \theta)$

- Interest : much faster than MCMC solutions

# VBEM algorithm

We can prove that for any distribution  $q_s(s)$  on the hidden variables :

$$\begin{aligned}\ln p(y|\theta) &= \ln \int \int p(s, y, \theta) ds d\theta \\ &\geq \ln p(y) - KL(q_{s,\theta}(\cdot) | p_{s,\theta}(\cdot|y))\end{aligned}$$

- We choose separable distributions  $q_{s,\theta}(\cdot) = q_s(s)q_\theta(\theta)$
- $q_s(s)$  is an approximation of  $p(s|y)$
- $q_\theta(\theta)$  is an approximation of  $p(\theta|y)$  We note :

$$\begin{aligned}\ln p(y) &\geq \ln p(y) - KL(q_{s,\theta}(\cdot) | p_{s,\theta}(\cdot|y)) \\ &\equiv \mathcal{F}(q_s(s), q_\theta(\theta))\end{aligned}$$

- E step :  $q_s^{(t+1)} = \operatorname{argmax}_{q_s \in \mathcal{Q}} \mathcal{F}(q_s(s), q_\theta^{(t)}(\theta))$
- M step :  $q_\theta^{(t+1)} = \operatorname{argmax}_{q_\theta \in \mathcal{Q}'} \mathcal{F}(q_s^{(t+1)}(s), q_\theta(\theta))$

# E step

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Result : explicit expression for  $q_{S_j}(S_j), j = 1 \dots N$  but not a classical distribution :

$$q_{S_j}(S_j) \propto \exp(-\mathbb{E}_{q_\theta}[e^\beta] e^{S_j} |A_j| + Y_j S_j) \exp\left(-\frac{(S_j - m_j)^2}{2\sigma_j^2}\right)$$

where  $\forall j = 1 \dots N, \sigma_j^2 = \frac{1}{\mathbb{E}_{q_\theta}[(\Sigma^{-1})_{jj}]}$

and  $\forall j = 1 \dots N, m_j = -\sigma_j^2 \sum_{l \neq j} \mathbb{E}_{q_\theta}[(\Sigma^{-1})_{jl}] \mathbb{E}_{q_{S_l}}[S_l]$

Problem : how to compute  $\mathbb{E}_{q_{S_j}}[S_j], \mathbb{E}_{q_{S_j}}[S_j^2]$  and  $\mathbb{E}_{q_{S_j}}[\exp(S_j)]$  needed for the M step ?

# E step : proposition

$\forall j = 1 \dots N,$

$$\begin{aligned} \mathsf{E}_{q_{S_j}}[S_j] &= \int K \exp(-\mathsf{E}_{q_\theta}[e^\beta] e^{S_j} |A_j| + Y_j S_j) \exp\left(-\frac{(S_j - m_j)^2}{2\sigma_j^2}\right) \\ &= \mathsf{E}_{\mathcal{N}(m_j, \sigma_j^2)}[K' \exp(-\mathsf{E}_{q_\theta}[e^\beta] e^{S_j} |A_j| + Y_j S_j) S_j] \end{aligned}$$

→ Monte-Carlo estimation

## E step

iterate on

- ① estimation of  $\mathsf{E}_{q_{S_j}}[S_j], j = 1 \dots N$  from simulations according to  $\mathcal{N}(m_j, \sigma_j^2)$

- ② evaluation of  $m_j, j = 1 \dots N$  from the  $\mathsf{E}_{q_{S_j}}[S_j], j = 1 \dots N$

evaluation of the other quantities ( $\mathsf{E}_{q_{S_j}}[S_j^2]$  and  $\mathsf{E}_{q_{S_j}}[\exp(S_j)]$ ) again from simulations according to  $\mathcal{N}(m_j, \sigma_j^2)$

# M step : proposition

Result :  $q_{\theta}(\theta) \propto q_{\beta}(\beta)q_{\sigma,\alpha}(\sigma, \alpha)$  where

$$q_{\beta}(\beta) \propto \exp \left( \sum_{k=1 \dots N} \left( -e^{\beta} |A_k| \mathsf{E}_{q_{S_k}}[e^{S_k}] + \beta y_k \right) \right) p(\beta)$$

$$\begin{aligned} q_{\sigma,\alpha}(\sigma, \alpha) &\propto \frac{1}{|\Sigma|^{1/2}} \exp \left( -\frac{1}{2} \sum_{k=1 \dots N} \left( (\Sigma^{-1})_{kk} q_{S_k}[S_k^2] + q_{S_k}[S_k] \right. \right. \\ &\quad \left. \left. \sum_{l \neq k} (\Sigma^{-1})_{kl} \mathsf{E}_{q_{S_l}}[S_l] \right) \right) p(\sigma)p(\alpha) \end{aligned}$$

→ non classical distributions

→ again evaluation of the  $\mathsf{E}_{q_{\beta}}[e^{\beta}]$  and  $\mathsf{E}_{q_{\sigma,\alpha}}[\Sigma^{-1}]$  from simulations according to the *a priori* laws

# Evaluation

- grid size :  $10 \times 40$  ( $N = 400$ )
- quadrat size :  $0.6m$  ( $\forall j, |A_j| = 0.36m^2$ )

## a priori laws

$$\beta \sim \mathcal{N}(0, 0.1), \ln \sigma \sim \mathcal{N}(0, 0.05), \ln \alpha \sim \mathcal{N}(0, 0.2)$$

## one experiment ( $\times N_S = 50$ )

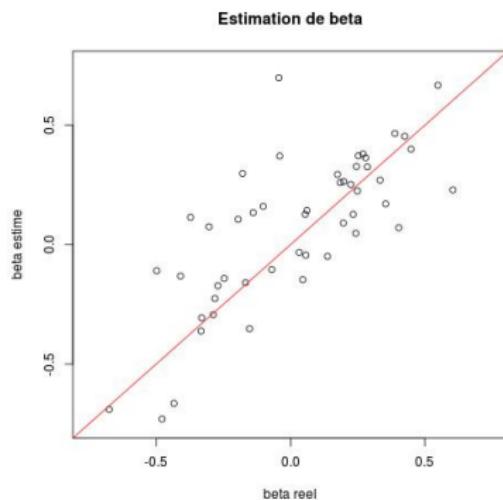
- ① generate parameters  $\alpha, \beta$  et  $\sigma$  from the *a priori* law
- ② generate the hidden Gaussian field  $S = \{S_j, j = 1 \dots N\}$  at each quadrat center
- ③ generate counts  $Y = \{Y_j, j = 1 \dots N\}$  at each quadrat
- ④ estimation of  $S$  and parameters from counts using VBEM and MCMC

# Estimation of $\beta$

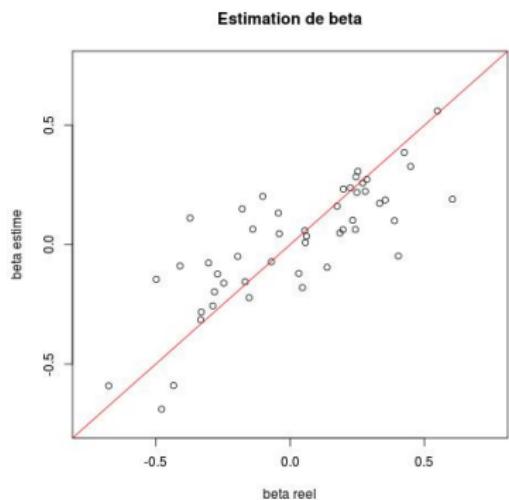
$$\lambda_x = \exp(\beta + S_x), \Sigma_{xx'} = \sigma^2 \exp(-\alpha \|x - x'\|)$$

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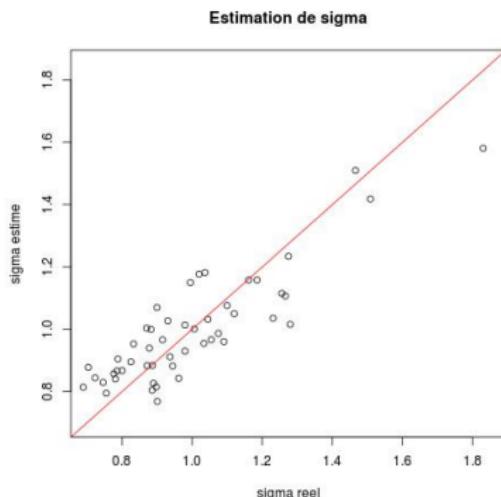
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# Estimation of $\sigma$

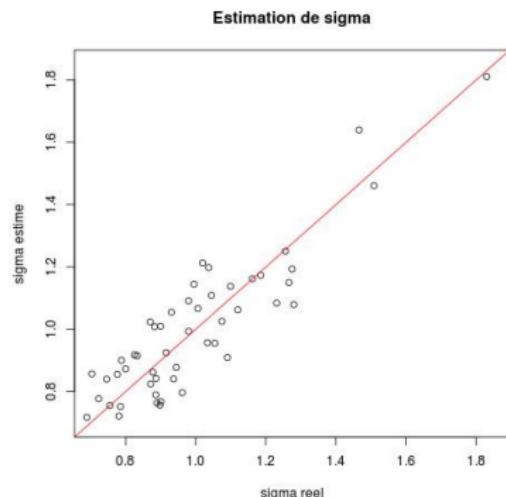
$$\lambda_x = \exp(\beta + S_x), \Sigma_{xx'} = \sigma^2 \exp(-\alpha \|x - x'\|)$$

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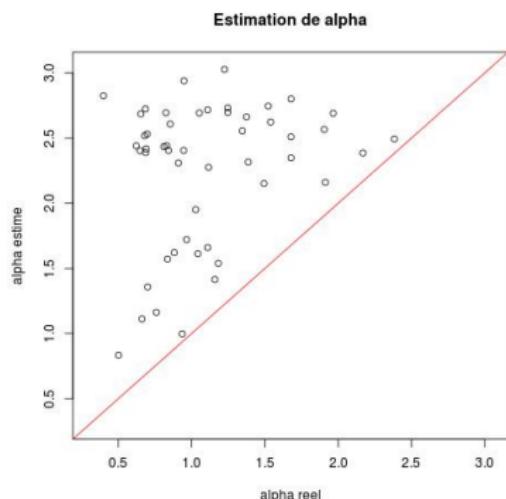
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# Estimation of $\alpha$

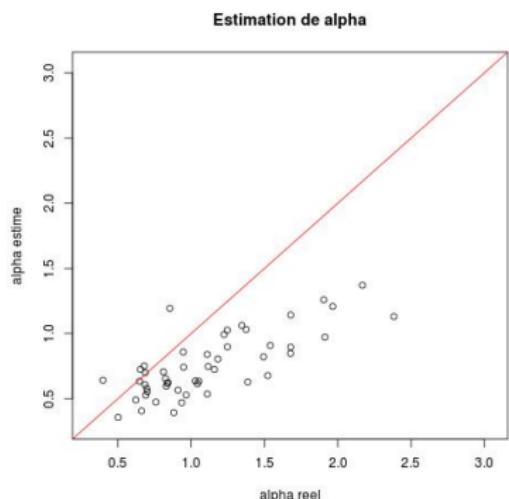
$$\lambda_x = \exp(\beta + S_x), \Sigma_{xx'} = \sigma^2 \exp(-\alpha \|x - x'\|)$$

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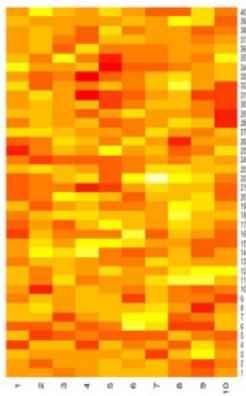
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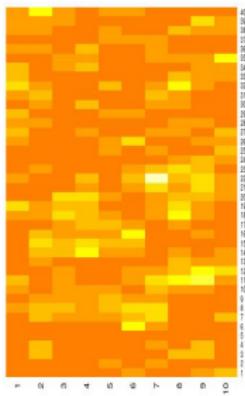
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# Example of hidden field $S$

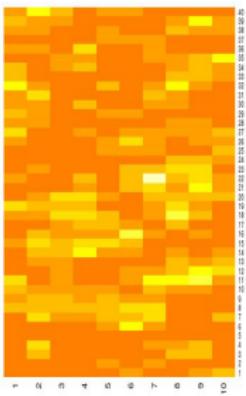
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simulation



VBEM



MCMC

# Mean Square Error

$$\text{MSE}(\hat{\beta}) = \frac{1}{N_S} \sum_{i=1}^{N_S} (\hat{\beta}_i - \beta_i)^2$$

$$\text{MSE}(\hat{S}) = \frac{1}{N \times N_S} \sum_{i=1}^{N_S} \sum_{j=1}^N (\hat{S}_j^i - S_j^i)^2$$

	$\beta$	$\sigma$	$\alpha$	$S$
VBEM	0.052	0.012	1.69	0.56
MCMC	0.034	0.011	0.22	0.52

→ similar MSE except for  $\alpha$

# Conclusions and Perspectives

- New methods for parameters estimation in a log-Gaussian Cox process
- MCEM more precise but more time-consuming than the moments method
- VBEM much faster than MCMC for bayesian estimation of LGCP (24h vs 12 min)
- Similar estimation quality for VBEM and MCMC except for  $\alpha$
- Comparison with INLA in a Bayesian framework (Rue et al., 2009)
- Comparison MCEM and VEM in a frequentist framework